

Topology Optimization of a Beam with Milling Constraints

This model is based on the Design Optimization of a Beam model. The model uses the Density Model feature to solve a structural topology optimization problem with milling constraints.

Model Definition

The model geometry (Figure 1) consists of two regions: A fixed domain on which a distributed load is applied and a design domain.

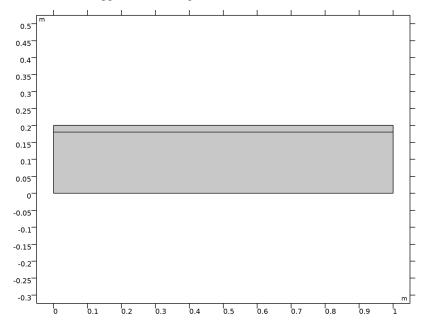


Figure 1: The model geometry with the Prescribed Material domain at the top.

The beam is made of aluminum and the displacement field is calculated under the assumption of linear elasticity. The displacement of the upper-right corner is constrained to be less than 0.2 mm.

For a detailed introduction to the use of structural topology optimization and how to use a Helmholtz filter for regularization, see the model Topology Optimization of an MBB Beam. The main points are that Young's modulus varies spatially to reflect the material distribution. It is not possible to set zero void stiffness, as this causes the void displacement

field to become undefined. This example considers milling constraints for the x and y directions, and this is implemented with two PDEs (n = 2):

$$\begin{split} 0 &\leq \theta_c \leq 1 \\ \theta_f &= \theta_c + R_{\min}^2 \nabla^2 \theta_f \\ 0 &= \hat{\mathbf{m}}_{\text{mil}}^i \cdot \nabla \theta_m^i \quad , \quad \left| \hat{\mathbf{m}}_{\text{mil}}^i \right| = 1 \\ \theta_m &= \left[\sum_{i=1}^n ((\theta_m^i)^{-p_{\text{mil}}}) / n \right]^{-1/p_{\text{mil}}} \\ \theta &= \frac{(\tanh(\beta(\theta_f - \theta_\beta)) + \tanh(\beta\theta_\beta))}{(\tanh(\beta(1 - \theta_\beta)) + \tanh(\beta\theta_\beta))} \\ \theta_p &= \theta_{\min} + (1 - \theta_{\min}) \theta^p \\ E &= E_0 \theta_p \end{split}$$

The approach is inspired by Ref. 1, which uses a finite volume discretization, but in this case a stabilized finite element method is used to solve the convective equations.

Figure 2 displays the result of optimization together with the distributed load and the mesh. The displacement field is shown in colors and the maximum value is located near the end of the beam.

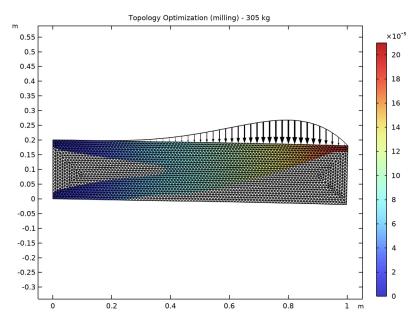


Figure 2: The optimization removes material from both milling directions to reduce the mass as much as possible without violating the displacement constraint in the upper right corner.

Notes About the COMSOL Implementation

This model combines the **Topology Optimization** and **Solid Mechanics** interfaces. In this case, the default values of the **Density Model** work well, but for more complicated 3D problems it might be beneficial to apply a continuation strategy in p, β , and p_{mil} . The model opts for smooth results in postprocessing by using a linear discretization for the milling variables, θ_m^i , but you can also use a constant discretization.

The model is nonlinear but only in the sense that it consists of a series of linear coupled problems. Therefore a **Segregated** solver can compute the solution in a single iteration.

Finally, the **Optimization** study step is recycled from the Design Optimization of a Beam model, but one could equally well have used a **Topology Optimization** study step in which case the move limit could be defined in that step. Using MMA instead of (the default)

GCMMA would still require changing a setting on the **Optimization Solver** node. However, this is not strictly necessary, so the model can be solved without editing the solver sequence if a longer computational time is acceptable.

Reference

1. L Høghøj and E.A. Träff, "An advection-diffusion based filter for machinable designs in topology optimization," Comp. Meth. App. Mech. & Eng., vol. 391, p. 114488, 2022.

Application Library path: Optimization Module/Topology Optimization/ beam optimization milling

Modeling Instructions

APPLICATION LIBRARIES

- I From the File menu, choose Application Libraries.
- 2 In the Application Libraries window, select Optimization Module > Design Optimization > beam optimization in the tree.
- 3 Click Open.

PARAMETER OPTIMIZATION, SHAPE OPTIMIZATION

- I In the Model Builder window, Ctrl-click to select Parameter Optimization and Shape Optimization.
- 2 Right-click and choose Delete.

COMPONENT I (COMPI)

In the Model Builder window, expand the Component I (compl) node.

SHAPE OPTIMIZATION

In the Model Builder window, expand the Component I (compl)>Shape Optimization node.

Free Shape Domain I, Polynomial Boundary I, Symmetry/Roller I

- I In the Model Builder window, under Component I (compl)>Shape Optimization, Ctrl-click to select Free Shape Domain I, Polynomial Boundary I, and Symmetry/Roller I.
- 2 Right-click and choose **Delete**.

3 Right-click Shape Optimization and choose Delete.

GLOBAL DEFINITIONS

Parameters 1

- I In the Model Builder window, expand the Topology Optimization node, then click Global Definitions>Parameters I.
- 2 In the Settings window for Parameters, locate the Parameters section.
- **3** In the table, enter the following settings:

Name	Expression	Value	Description
volfrac	0.4	0.4	Volume fraction
meshsz	1[cm]	0.01 m	Mesh size

TOPOLOGY OPTIMIZATION

Density Model I (dtopol)

- I In the Model Builder window, under Component I (compl)>Topology Optimization click Density Model I (dtopol).
- 2 In the Settings window for Density Model, click to expand the Milling section.
- 3 From the Milling constraints list, choose Enabled.
- 4 Click + Add.
- **5** In the table, enter the following settings:

X	Y
0	1
1	0

- **6** Locate the **Filtering** section. From the R_{\min} list, choose **User defined**.
- 7 In the text field, type meshsz.
- **8** Locate the **Projection** section. From the **Projection type** list, choose **Hyperbolic tangent projection**.
- **9** Locate the Control Variable Initial Value section. In the θ_0 text field, type 0.1.

MESH I

Free Triangular 2

In the Mesh toolbar, click Free Triangular.

Size

- I In the Model Builder window, click Size.
- 2 In the Settings window for Size, click to expand the Element Size Parameters section.
- 3 In the Maximum element size text field, type meshsz.

TOPOLOGY OPTIMIZATION

Optimization

- I In the Model Builder window, expand the Topology Optimization node, then click Optimization.
- 2 In the Settings window for Optimization, locate the Optimization Solver section.
- 3 Find the Solver settings subsection. In the Maximum number of model evaluations text field, type 1000.
- 4 Click Replace Expression in the upper-right corner of the Objective Function section. From the menu, choose Component I (compl)>Definitions>Density Model I>Global> compl.dtopol.theta_avg - Average material volume factor.
- **5** Locate the **Objective Function** section. In the table, enter the following settings:

Expression	Description	Evaluate for
comp1.dtopo1.theta_avg/ volfrac	Average material volume factor	Stationary

Solver Configurations

In the Model Builder window, expand the Topology Optimization>Solver Configurations node.

Solution 5 (sol5)

- I In the Model Builder window, expand the Topology Optimization>Solver Configurations> Solution 5 (sol5) node.
- 2 Right-click Dependent Variables I and choose Update Variables.
- 3 In the Settings window for Optimization Solver, locate the Optimization Solver section.
- 4 Select the Maximum number of outer iterations check box. In the associated text field, type 50.
- **5** Clear the **Globally Convergent MMA** check box.
- 6 Select the Move limits check box.
- 7 In the Model Builder window, expand the Topology Optimization>Solver Configurations> Solution 5 (sol5)>Optimization Solver I>Stationary I node.

- 8 Right-click Stationary I and choose Segregated.
- 9 In the Settings window for Segregated, locate the General section.
- **10** From the Termination technique list, choose Iterations.
- II Right-click Segregated I and choose Segregated Steptwice.
- **12** In the **Settings** window for **Segregated Step**, type Solid Mechanics in the **Label** text field.
- 13 Locate the General section. Under Variables, click + Add.
- 14 In the Add dialog box, in the Variables list, choose Control material volume factor (compl.dtopol.theta_c) and Displacement field (compl.u).
- IS Click OK.
- 16 In the Model Builder window, under Topology Optimization>Solver Configurations> Solution 5 (sol5)>Optimization Solver I>Stationary I>Segregated I click Segregated Step I.
- 17 In the Settings window for Segregated Step, type Milling in the Label text field.
- **18** Locate the **General** section. Under **Variables**, click + **Add**.
- 19 In the Add dialog box, in the Variables list, choose Control material volume factor (compl.dtopol.theta_c), Milling material volume factor (compl.dtopol.theta_ml), and Milling material volume factor (compl.dtopol.theta_m2).
- 20 Click OK.
- 21 In the Model Builder window, under Topology Optimization>Solver Configurations>
 Solution 5 (sol5)>Optimization Solver I>Stationary I>Segregated I click Segregated Step.
- **22** In the **Settings** window for **Segregated Step**, type Optimization in the **Label** text field.
- 23 Locate the General section. In the Variables list, choose

 Milling material volume factor (compl.dtopol.theta_ml), Displacement field (compl.u),
 and Milling material volume factor (compl.dtopol.theta_m2).
- 24 Under Variables, click Delete.

RESULTS

Topology Optimization

- I In the Model Builder window, expand the Results node, then click Topology Optimization.
- 2 In the Settings window for 2D Plot Group, click to expand the Title section.
- 3 In the Title text area, type Topology Optimization (milling) eval(mass1.mass) kg.

- 4 From the Number format list, choose Stopwatch.
- 5 In the Number of decimals text field, type 0.

TOPOLOGY OPTIMIZATION

Optimization

In the **Home** toolbar, click **Compute**.

RESULTS

Topology	Optimization
Click the	Zoom Extents button in the Graphics toolbar