

Piezoelectric Shear-Actuated Beam

Introduction

This example performs a static analysis on a piezoelectric actuator based on the movement of a cantilever beam, using the Piezoelectricity predefined multiphysics interface. Inspired by work done by V. Piefort (Ref. 1) and A. Benjeddou (Ref. 2), it models a sandwich beam using the shear mode of the piezoelectric material to deflect the tip.

Model Definition

GEOMETRY

The model consists of a 100-mm long sandwiched cantilever beam (Figure 1).

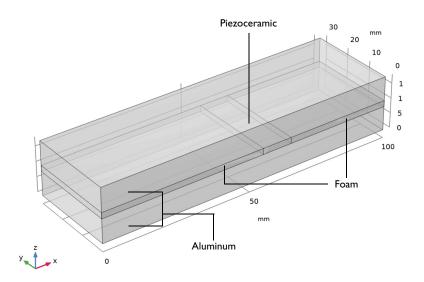


Figure 1: The shear bender geometry. Note that a piezoceramic material replaces part of the foam core.

This beam is composed of a 2-mm thick flexible foam core sandwiched by two 8-mm thick aluminum layers. Furthermore, the device replaces part of the foam core with a 10-mm long piezoceramic actuator that is positioned between x = 55 mm and x = 65 mm. The cantilever beam is orientated along the global *x*-axis.

BOUNDARY CONDITIONS

- *Solid Mechanics:* the cantilever beam is fixed at its surfaces at *x* = 0; all other surfaces are free.
- *Electrostatics:* The system applies a 20 V potential difference between the top and bottom surfaces of the piezoceramic domain (Figure 2). This gives rise to an electric field perpendicular to the poling direction (x direction) and thus induces a transverse shear strain.

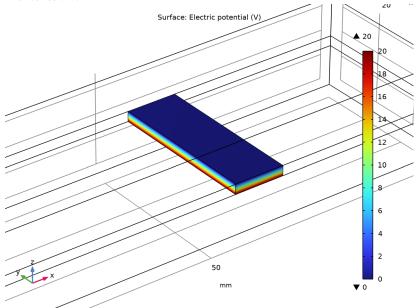


Figure 2: Applied voltage through the piezoelectric material

MATERIAL PROPERTIES

The following table lists the material properties for the aluminum layers and the foam core:

Property	Aluminum	Foam	Piezoceramic
E	70 GPa	35.3 MPa	-
ν	0.35	0.383	-
ρ	2700 kg/m ³	32 kg/m ³	7500 kg/m ³

Aluminum is available as a predefined material, whereas you must define the foam material manually.

The piezoceramic material in the actuator, PZT-5H, is already defined in the material library. Thus, you do not need to enter the components of the elasticity matrix, c_E , the piezoelectric coupling matrix, e, or the relative permittivity matrix, ε_{rS} .

Results

The shear deformation of the piezoceramic core layer and the flexible foam layer induce a bending action. Figure 3 shows the resulting tip deflection. The model calculates this deflection as 83 nm, a result that agrees well with those of Ref. 1 and Ref. 2.

Volume: Displacement field, Z-component (nm)

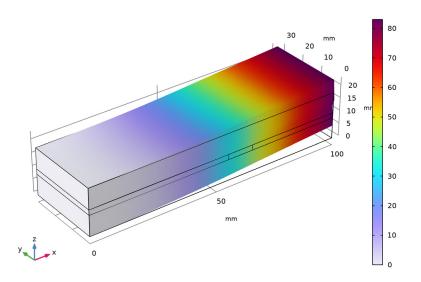
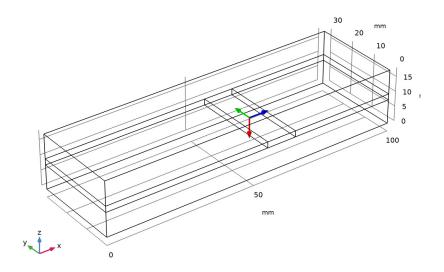


Figure 3: Tip deflection with the piezoceramic positioned at x = 60 mm.

Notes About the COMSOL Implementation

The matrix components for the piezoelectric material properties refer to a coordinate system, where the poling direction is the z direction. Because the poling direction of the piezoceramic actuator in this model is aligned with the *x*-axis, you need to use a local coordinate system in the material settings to rotate the piezoceramic material.

More specifically, you define a local coordinate system that is rotated 90 degrees about the global *y*-axis. Then, you use this coordinate system in the piezoelectric material settings to rotate the material so that the polarization direction is aligned with the *x*-axis (Figure 4).



Coordinate system volume: Base vector system

Figure 4: Definition of local coordinate system to define the piezoelectric orientation. The material is poled along the local x3 direction (blue arrow).

References

1. V. Piefort, *Finite Element Modelling of Piezoelectric Active Structures*, Ph.D. thesis, Université Libre de Bruxelles, Belgium, Dept. Mechanical Engineering and Robotics, 2001.

2. A. Benjeddou, M.A. Trindade, and R. Ohayon, A Unified Beam Finite Element Model for Extension and Shear Piezoelectric Actuation Mechanisms, CNAM (Paris, France), Structural Mechanics and Coupled Systems Laboratory, 1997.

Application Library path: MEMS_Module/Piezoelectric_Devices/shear_bender

Modeling Instructions

From the File menu, choose New.

NEW

In the New window, click 🔗 Model Wizard.

MODEL WIZARD

- I In the Model Wizard window, click 间 3D.
- 2 In the Select Physics tree, select Structural Mechanics>Electromagnetics-Structure Interaction>Piezoelectricity>Piezoelectricity, Solid.
- 3 Click Add.
- 4 Click 🔿 Study.
- 5 In the Select Study tree, select General Studies>Stationary.
- 6 Click 🗹 Done.

GEOMETRY I

- I In the Model Builder window, under Component I (compl) click Geometry I.
- 2 In the Settings window for Geometry, locate the Units section.
- 3 From the Length unit list, choose mm.

Block I (blkI)

- I In the **Geometry** toolbar, click 🗍 **Block**.
- 2 In the Settings window for Block, locate the Size and Shape section.
- **3** In the **Width** text field, type 100.
- 4 In the **Depth** text field, type 30.
- 5 In the **Height** text field, type 18.
- 6 Click 🔚 Build Selected.

Block 2 (blk2)

- I In the **Geometry** toolbar, click 🗍 **Block**.
- 2 In the Settings window for Block, locate the Size and Shape section.
- **3** In the **Width** text field, type 100.
- 4 In the **Depth** text field, type 30.
- 5 In the Height text field, type 2.
- 6 Locate the **Position** section. In the **z** text field, type 8.

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- 7 Click to expand the Layers section. Find the Layer position subsection. Select the Left check box.
- 8 Clear the **Bottom** check box.
- 9 In the table, enter the following settings:

Layer name	Thickness (mm)		
Layer 1	55		
Layer 2	10		

IO Click 🟢 Build All Objects.

II Click the 🕂 Zoom Extents button in the Graphics toolbar.

The model geometry is now complete.

12 Click the **Transparency** button in the **Graphics** toolbar.

The geometry in the **Graphics** window should now look like that in Figure 1.

I3 Click the **Transparency** button in the **Graphics** toolbar.

DEFINITIONS

Define a coordinate system whose third axis is aligned with the global x-axis, that is, the polarization direction of the piezoceramic material. Choose the second axis to be parallel to the global y-axis.

Base Vector System 2 (sys2)

I In the Definitions toolbar, click $\swarrow^{z,y}$ Coordinate Systems and choose Base Vector System.

2 In the Settings window for Base Vector System, locate the Base Vectors section.

3 In the table, enter the following settings:

	x	у	Z
xl	0	0	-1
x3	1	0	0

Leave the other components at their default values. You will use this coordinate system in the piezoelectric material settings.

4 Find the Simplifications subsection. Select the Assume orthonormal check box.

ELECTROSTATICS (ES)

- I In the Model Builder window, under Component I (compl) click Electrostatics (es).
- 2 In the Settings window for Electrostatics, locate the Domain Selection section.

3 Click Clear Selection.

4 Select Domain 4 only.

SOLID MECHANICS (SOLID)

Piezoelectric Material I

- I In the Model Builder window, under Component I (comp1)>Solid Mechanics (solid) click Piezoelectric Material I.
- 2 In the Settings window for Piezoelectric Material, locate the Domain Selection section.
- 3 Click Clear Selection.
- **4** Select Domain 4 only.
- 5 Locate the Coordinate System Selection section. From the Coordinate system list, choose Base Vector System 2 (sys2).

MATERIALS

For the aluminum layers, use a library material.

ADD MATERIAL

- I In the Home toolbar, click 🙀 Add Material to open the Add Material window.
- 2 Go to the Add Material window.
- 3 In the tree, select MEMS>Metals>Al Aluminum.
- 4 Click Add to Component in the window toolbar.

MATERIALS

AI - Aluminum (mat1)

- I In the Settings window for Material, locate the Geometric Entity Selection section.
- 2 Click Clear Selection.
- **3** Select Domains 1 and 3 only.

For the foam core, specify the material properties by hand.

Foam

- I In the Model Builder window, right-click Materials and choose Blank Material.
- 2 In the Settings window for Material, type Foam in the Label text field.
- **3** Select Domains 2 and 5 only.

4 Locate the Material Contents section. In the table, enter the following settings:

Property	Variable	Value	Unit	Property group
Young's modulus	E	35.3[MPa]	Pa	Young's modulus and Poisson's ratio
Poisson's ratio	nu	0.383	I	Young's modulus and Poisson's ratio
Density	rho	32	kg/m³	Basic

The piezoceramic PZT-5H is available as a predefined material.

ADD MATERIAL

- I Go to the Add Material window.
- 2 In the tree, select Piezoelectric>Lead Zirconate Titanate (PZT-5H).
- 3 Click Add to Component in the window toolbar.

Add Material

- I From the Home menu, choose Add Material.
- **2** Select Domain 4 only.

SOLID MECHANICS (SOLID)

Fixed Constraint 1

- I In the Model Builder window, expand the Component I (comp1)>Materials>Foam (mat2) node.
- 2 Right-click Component I (comp1)>Solid Mechanics (solid) and choose Fixed Constraint.
- **3** Select Boundaries 1, 4, and 7 only.

ELECTROSTATICS (ES)

In the Model Builder window, under Component I (compl) click Electrostatics (es).

Electric Potential 1

- I In the Physics toolbar, click 🔚 Boundaries and choose Electric Potential.
- **2** Select Boundary 16 only.
- 3 In the Settings window for Electric Potential, locate the Electric Potential section.
- **4** In the V_0 text field, type 20.

Ground I

I In the Physics toolbar, click 🔚 Boundaries and choose Ground.

2 Select Boundary 17 only.

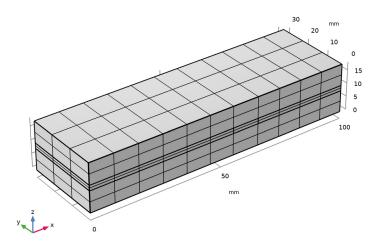
MESH I

Swept / In the Mesh toolbar, click Ass Swept.

Distribution I

- I Right-click Swept I and choose Distribution.
- 2 In the Settings window for Distribution, locate the Distribution section.
- 3 In the Number of elements text field, type 2.
- 4 Click 📗 Build All.
- **5** Click the \leftarrow **Zoom Extents** button in the **Graphics** toolbar.

The mesh consists of 198 hexahedral elements.



STUDY I

In the **Home** toolbar, click **= Compute**.

RESULTS

Displacement (solid)

Replace the default stress plot by displacement to reproduce the plot shown in Figure 3.

I In the **Settings** window for **3D Plot Group**, type Displacement (solid) in the **Label** text field.

Volume 1

- I In the Model Builder window, expand the Displacement (solid) node, then click Volume I.
- 2 In the Settings window for Volume, click Replace Expression in the upper-right corner of the Expression section. From the menu, choose Component I (compl)>Solid Mechanics> Displacement>Displacement field - m>w - Displacement field, Z-component.
- 3 Locate the Expression section. From the Unit list, choose nm.
- **4** In the **Displacement (solid)** toolbar, click **O Plot**.
- **5** Click the **J Go to Default View** button in the **Graphics** toolbar.

Electric Potential (es)

In the Model Builder window, expand the Electric Potential (es) node.

Multislice I, Streamline Multislice I

- I In the Model Builder window, under Results>Electric Potential (es), Ctrl-click to select Multislice I and Streamline Multislice I.
- 2 Right-click and choose Delete.

Surface 1

- I In the Model Builder window, right-click Electric Potential (es) and choose Surface.
- In the Settings window for Surface, click Replace Expression in the upper-right corner of the Expression section. From the menu, choose Component I (compl)>Electrostatics> Electric>V Electric potential V.
- 3 In the Electric Potential (es) toolbar, click 🗿 Plot.

Zoom in to find a plot similar to Figure 2.

- **4** Click the \bigcirc **Zoom In** button in the **Graphics** toolbar.
- **5** Click the **Com Extents** button in the **Graphics** toolbar.

Show the base vector that defines the polarization of the piezoelectric material, shown on Figure 4.

PZT coordinate system

- I In the Home toolbar, click 🚛 Add Plot Group and choose 3D Plot Group.
- 2 In the Settings window for 3D Plot Group, type PZT coordinate system in the Label text field.

Coordinate System Volume 1

- I In the PZT coordinate system toolbar, click i More Plots and choose Coordinate System Volume.
- **2** In the **Settings** window for **Coordinate System Volume**, locate the **Coordinate System** section.
- **3** From the Coordinate system list, choose Base Vector System 2 (sys2).
- 4 Locate the **Positioning** section. Find the **x grid points** subsection. From the **Entry method** list, choose **Coordinates**.
- **5** In the **Coordinates** text field, type **60**.
- 6 Find the y grid points subsection. In the Points text field, type 1.
- 7 Find the z grid points subsection. In the Points text field, type 1.
- 8 In the PZT coordinate system toolbar, click **I** Plot.