

Energy-Based Thermal Fatigue Prediction in a Ball Grid Array

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Introduction

In a cooling system, a microelectronic component has been identified as the critical link. Since the power is repeatedly switched on and off, the component is subjected to thermal cycling. As a result, a crack grows through a solder joint and disconnects the chip from the printed circuit board, causing a malfunction. In the simulation, the solder lifetime in two ball grid assemblies is predicted. The prediction is based on the Darveaux energy-based model. The fatigue model evaluates damage based on an averaged energy dissipation density in a thin layer, where a crack is expected to grow.

This example is based on a model from the Nonlinear Structural Materials Module — Viscoplastic Solder Joints. Since the model contains several solder joints that are modeled with a viscoplastic material, many degrees of freedom are required in order to simulate the correct creep behavior in all elements. From the fatigue point of view, only the critical part of the model is of interest. In order to capture it, the concept of submodeling is used. This technique consists of two steps. In the first one, the full model is analyzed with a coarse mesh in order to capture the general trends and to identify the critical part of the model. In the second step a fine submodel containing the critical part is made and the study is resolved. The global effects from the full model are transferred to the submodel via appropriate boundary conditions.

Model Definition

The microelectronic component consists of a flat printed circuit board that is covered with a thin copper layer. Two microprocessors are connected to the copper layer with a ball grid array of 60Sn-40Pb solder joints; see Figure 1.

Both microprocessors generate power when they are switched on and when they are in stand-by. This generates heat throughout its operational lifetime. The power cycle is at its maximum, $5 \cdot 10^7 \text{ W/m}^3$, during 4 h and at its minimum $1 \cdot 10^7 \text{ W/m}^3$, during 2 h. The switch between high and low power is not instantaneous, but takes few minutes.

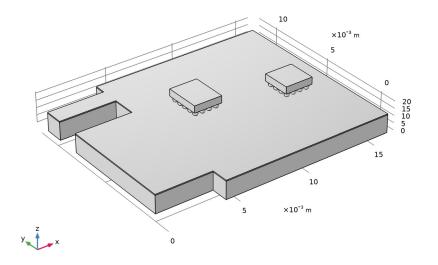


Figure 1: Geometry of the microelectronic component.

The elastic and thermal properties of the material can be taken from the built-in material library in COMSOL Multiphysics. The heat transfer coefficient for all free surfaces can be approximated with 10 W/(m²·K). The nonlinear behavior of the solder material follows the Anand material model with parameters summarized in Table 1.

PROPERTY	VALUE	DESCRIPTION	
Α	1.49·10 ⁷ 1/s	Pre-exponential factor	
Q	90046 J/mol	Activation energy/Boltzmann constant	
ξ	11	Stress multiplier	
т	0.303	Strain rate sensitivity of stress	
$s_{ m sat}$	80.42 MPa	Coefficient for deformation resistance saturation	
$s_{ m init}$	56.33 MPa	Initial value of deformation resistance	
h_0	2640.75 MPa	Hardening coefficient	
a	1.34	Strain rate sensitivity of hardening	
n	0.0231	Sensitivity for deformation resistance	

TABLE I: CONSTANTS OF THE ANAND MODEL.

The Darveaux fatigue model is representative for life prediction of the solder material. The model combines life contributions from crack initiation and crack propagation using the expression

$$N = K_1 \left(\frac{\Delta W_{\text{ave}}}{W_{\text{ref}}}\right)^{k_2} + \frac{a}{K_3 \left(\frac{\Delta W_{\text{ave}}}{W_{\text{ref}}}\right)^{k_4}}$$

where N is the fatigue life given in number of cycles, ΔW_{ave} is the averaged dissipated energy density in a fatigue cycle, *a* is the distance the crack needs to propagate for the failure to occur, and K_1, k_2, K_3, k_4 , and W_{ref} are material constants. The numerical values of the material constants are given in Table 2.

TABLE 2: FATIGUE MATERIAL PARAMETERS.

PROPERTY	VALUE	DESCRIPTION
K_1	13173	Crack initiation energy coefficient
k_2	-1.45	Crack initiation energy exponent
K_3	3.92·10 ⁻⁷ in	Crack propagation energy coefficient
k_4	1.12	Crack propagation energy exponent
W_{ref}	l psi ³	Reference energy density

The distance *a* is in this analysis be taken to be $2.6457 \cdot 10^{-4}$ in. This is based on the assumption that the problem is not symmetric and a crack is expected to start on one side of the joint only and not all around the joint at the same time.

The concept of submodeling is utilized in this example. This technique requires that first an analysis of the full model is performed in order to capture general trends, followed by an analysis of a submodel that is studied in detail. The following steps are done:

- I A coupled structural and thermal analysis is performed during four load cycles on the full model. Since the model contains several solder joints, a coarse mesh is used. All joints are meshed in the same way in order to minimize numerical discrepancies that are mesh dependent.
- **2** A fatigue prediction is made on the fourth cycle. The energy dissipation volume average and corresponding life is evaluated for each individual solder joint. The critical joint is identified.
- **3** A submodel of the critical joint with a fine mesh is created. The displacements from step 1 are prescribed as **Prescribed Displacement** on the boundaries where the submodel is cut out of the full model. Similarly, the temperature from step 1 is prescribed as a

Temperature in the heat transfer analysis of the submodel. This is done for all time steps of the four simulated cycles.

4 A fatigue analysis is performed on the critical solder joint in the submodel. A life prediction is made based on the energy dissipation in a 50 μm thick layer. Two layers are evaluated. One that is in connection with the copper side and one that is in connection with the microchip side.

The submodel is shown in Figure 2. The purple color denotes the boundaries where the results from the structural analysis of the global model are prescribed. The solder joint is divided in three domains: a central one and two domains close to the interface to the other materials.

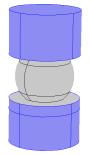


Figure 2: Submodel containing the critical joint.

Results and Discussion

The fatigue life prediction for all joints is shown in Figure 3. For both microchips, the critical joints are located in the corners of each ball grid array. This is expected, since those joints experience highest strains due to the differences in thermal properties. The solder joints of the microchip with the larger ball grid array shows a shorter life than the joints of the other microchip. The life prediction for all four corner joints is about the same, $5.8 \cdot 10^4$ cycles.

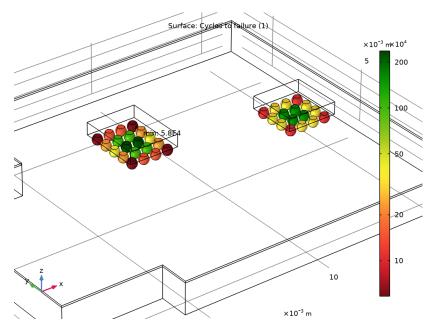


Figure 3: Fatigue life prediction for all joints based on the global model.

One of the four critical corner joints is reanalyzed in the submodel. In order to verify that the temperature is correctly prescribed in the submodel a comparison of the temperature history in a point on the upper sider of the joint is shown in Figure 4. The results of both models are in prefect match. Note that much fewer data points are stored for the submodel.

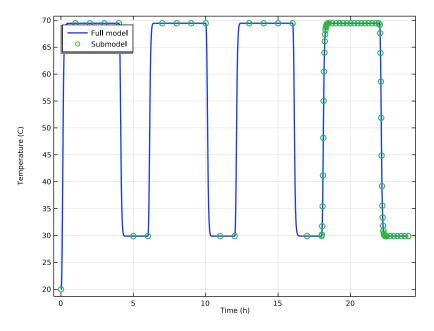


Figure 4: Temperature history for both the full model and the submodel.

A comparison of the dissipated energy in a point on the upper side of the joint is shown in Figure 5. The results differs between the two models. This difference is caused by the difference in the mesh. The finer mesh in the submodel is better than the coarser mesh of the full model in capturing the strain gradient close to the upper side of the solder joint. Note that much fewer data points are stored in the submodel for the first three cycles, hence, the presented results are not a smooth. This does not affect the accuracy of the solution.

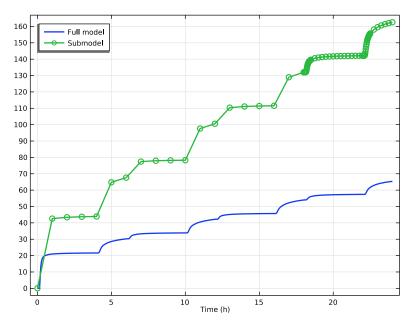


Figure 5: Comparison of the dissipated creep energy in both models.

The results of the fatigue analysis of the critical joint in the submodel are shown in Figure 6 and Figure 7. In the first figure, the fatigue life is based on the energy dissipation volume average evaluated over the whole joint, while in the second figure the volume average is performed over separate domains. The fatigue life predicted by different models is summarized in Table 3.

EVALUATION METHOD	FATIGUE LIFE (CYCLES)	SOURCE
Entire joint in the full model	5.8·10 ⁴	Figure 3
Entire joint in the submodel	8.1·10 ⁴	Figure 6
Thin layer in the submodel	9·10 ³	Figure 7

TABLE 3: FATIGUE LIFE BASED ON DIFFERENT MODELING TECHNIQUES.

The difference between the fatigue life prediction of the full model and of the submodel is small. It is however observed in real applications that a crack grows through a solder joint close to the interface and therefore a thin layer is required. If a thin layer were to be created in all joints of the full model, the simulation would require large computational resources. In the current example, the full model consists of about 170,000 DOFs while the submodel consists of 40,000 DOFs.

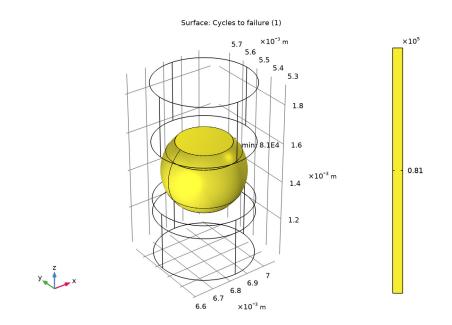


Figure 6: Fatigue prediction based on the volume average of the entire joint.

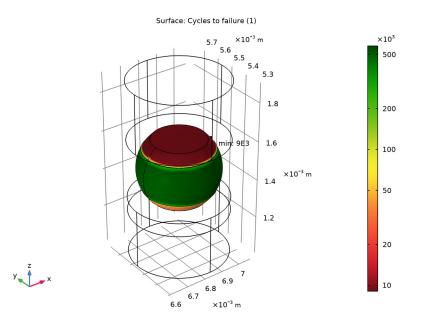


Figure 7: Fatigue prediction based on the volume average of different domains.

Notes About the COMSOL Implementation

In submodeling, the results are mapped from one component — a full model — to another one — a submodel. This is possible through the **General Extrusion** operator. In this example, the mapping of results is simple since it is 1 to 1. The **General Extrusion** operator allows also for mapping into other shapes.

Often, a load history in a fatigue study is repeatable. In order to write the cyclic function in a compact way, a modulo function can be used. This function calculates the reminder of a number, dividend, divided by an other number, divisor. In COMSOL Multiphysics it is defined as mod(f,p), where the first argument is the dividend and the second one is the divisor.

From the numerical point of view, an abrupt change in a load parameter can be challenging. In the current example, a sudden increase or decrease of the power provides such a challenge. In such a case it is favorable to use a smooth function that changes from one value to an other. This is possible in via flc2hs(t,p) function that is a Heaviside function with a smooth second derivative. The first argument defines a position when the

step takes place and the second argument defines an interval on each side of the step position where the smooth transition takes place.

Application Library path: Fatigue_Module/Energy_Based/ viscoplastic_solder_joints_fatigue

Modeling Instructions

In this example you will start from an existing model which is an example in the Nonlinear Structural Materials Module.

From the File menu, choose Open.

From the Application Libraries root, browse to the folder Nonlinear_Structural_Materials_Module/Viscoplasticity and double-click the file viscoplastic_solder_joints.mph.

FULL MODEL

- I In the Model Builder window, click Component I (compl).
- 2 In the Settings window for Component, type Full Model in the Label text field.

Define the crack size that will be used in crack models.

GLOBAL DEFINITIONS

Parameters 1

- I In the Model Builder window, under Global Definitions click Parameters I.
- 2 In the Settings window for Parameters, locate the Parameters section.
- **3** In the table, enter the following settings:

Name	Expression	Value	Description
lcrack	2.6457e-4[in]	6.7201E-6 m	Crack size

Define the power load cycle.

Analytic I (power)

- I In the Model Builder window, click Analytic I (power).
- 2 In the Settings window for Analytic, locate the Definition section.

3 In the Expression text field, type (flc2hs(x-0.1,0.1)*50)*(x<6)-flc2hs(mod(x, 6)-4.1,0.1)*40+(flc2hs(mod(x,6)-0.1,0.1)*40+10)*(x>=6).

FULL MODEL (COMPI)

Create a General Extrusion operator that will be used when the submodel is set up.

DEFINITIONS

General Extrusion 1 (genext1)

- I In the Model Builder window, expand the Full Model (compl) node.
- 2 Right-click Full Model (comp1)>Definitions and choose Nonlocal Couplings> General Extrusion.
- 3 In the Settings window for General Extrusion, locate the Source Selection section.
- 4 From the Selection list, choose All domains.

FULL MODEL: LOAD HISTORY

- I In the Model Builder window, click Study I.
- 2 In the Settings window for Study, type Full Model: Load History in the Label text field.

Step 1: Time Dependent

- I In the Model Builder window, expand the Full Model: Load History node, then click Step I: Time Dependent.
- 2 In the Settings window for Time Dependent, locate the Study Settings section.
- 3 In the Output times text field, type 0 0.005 range(0.025,0.025,0.5) range(0.75, 0.25,3.75) 3.975 4+{range(0,0.025,0.5) range(0.75,0.25,2)} 6+ {range(0.025,0.025,0.5) range(0.75,0.25,3.75) 3.975 4+{range(0,0.025, 0.5) range(0.75,0.25,2)} 12+{range(0.025,0.025,0.5) range(0.75,0.25, 3.75) 3.975 4+{range(0,0.025,0.5) range(0.75,0.25,2)} 18+ {range(0.025,0.025,0.5) range(0.75,0.25,3.75) 3.975 4+{range(0,0.025, 0.5) range(0.75,0.25,2)}.

Solver Configurations

In the Model Builder window, expand the Full Model: Load History>Solver Configurations node.

Step 2: Time Dependent 2

In the Times text field, enter the same steps as Step I.

- I In the Model Builder window, expand the Full Model: Load History>Solver Configurations> Solution I (soll) node.
- 2 Right-click Full Model: Load History and choose Compute.

RESULTS

Stress (solid)

Perform a fatigue study on the full model in order to find out which solder joint is the critical one.

ADD PHYSICS

- I In the Home toolbar, click 🙀 Add Physics to open the Add Physics window.
- 2 Go to the Add Physics window.
- 3 In the tree, select Structural Mechanics>Fatigue (ftg).
- 4 Find the Physics interfaces in study subsection. In the table, clear the Solve check box for Full Model: Load History.
- 5 Click Add to Full Model in the window toolbar.
- 6 In the Home toolbar, click 🙀 Add Physics to close the Add Physics window.

FATIGUE (FTG)

Energy-Based I

- I Right-click Full Model (compl)>Fatigue (ftg) and choose the domain evaluation Energy-Based.
- 2 In the Settings window for Energy-Based, locate the Domain Selection section.
- 3 From the Selection list, choose Solder.
- 4 Locate the Solution Field section. From the Physics interface list, choose Solid Mechanics (solid).
- 5 Locate the Fatigue Model Selection section. From the Criterion list, choose Darveaux.
- 6 From the Energy type list, choose Viscoplastic dissipation density.
- 7 Locate the Fatigue Model Parameters section. In the *a* text field, type lcrack.

ROOT

In the Model Builder window, expand the Full Model (compl)>Materials node.

GLOBAL DEFINITIONS

In the Model Builder window, expand the Global Definitions>Materials node.

Solder, 60Sn-40Pb (mat4)

- I In the Model Builder window, click Solder, 60Sn-40Pb (mat4).
- 2 In the Settings window for Material, locate the Material Contents section.
- **3** In the table, enter the following settings:

Property	Variable	Value	Unit	P roperty group
Crack initiation energy coefficient	KI_Darveau x	13173	I	Darveaux
Crack initiation energy exponent	k2_Darveau x	-1.45	I	Darveaux
Crack propagation energy coefficient	K3_Darveau x	3.92e- 7[in]	m	Darveaux
Crack propagation energy exponent	k4_Darveau x	1.12	I	Darveaux
Reference energy density	Wref_Darve aux	1[psi]	J/m³	Darveaux

ROOT

From the Home menu, choose Add Study.

ADD STUDY

- I Go to the Add Study window.
- 2 Find the Physics interfaces in study subsection. In the table, clear the Solve check boxes for Solid Mechanics (solid) and Heat Transfer in Solids (ht).
- 3 Find the Studies subsection. In the Select Study tree, select Preset Studies for Selected Physics Interfaces>Fatigue.
- 4 Click Add Study in the window toolbar.
- 5 From the Home menu, choose Add Study.

FULL MODEL: FATIGUE EVALUATION

- I In the Model Builder window, expand the Solder, 60Sn-40Pb (mat4) node, then click Study 2.
- 2 In the Settings window for Study, type Full Model: Fatigue Evaluation in the Label text field.

Step 1: Fatigue

I In the Model Builder window, under Full Model: Fatigue Evaluation click Step I: Fatigue.

- 2 In the Settings window for Fatigue, locate the Values of Dependent Variables section.
- **3** Find the Values of variables not solved for subsection. From the Settings list, choose User controlled.
- 4 From the Method list, choose Solution.
- 5 From the Study list, choose Full Model: Load History, Time Dependent 2.
- 6 From the Time (h) list, choose From list.
- 7 From the list, select time steps from 18h to 24h.
- 8 In the Home toolbar, click **=** Compute.

RESULTS

Cycles to Failure (ftg)

The solder joint with the shortest life is the critical one. Create a submodel of that joint.

ADD COMPONENT

In the Model Builder window, right-click the root node and choose Add Component>3D.

SUBMODEL

In the Settings window for Component, type Submodel in the Label text field.

GEOMETRY 2

Import I (imp1)

- I In the Home toolbar, click া Import.
- 2 In the Settings window for Import, locate the Import section.
- 3 Click *Browse*.
- 4 Browse to the model's Application Libraries folder and double-click the file viscoplastic solder joints.mphbin.
- 5 Click ा Import.

Cylinder I (cyl1)

- I In the **Geometry** toolbar, click 📗 **Cylinder**.
- 2 In the Settings window for Cylinder, locate the Size and Shape section.
- 3 In the Radius text field, type 2.4e-4.
- 4 In the Height text field, type 9e-4.
- 5 Locate the Position section. In the x text field, type 68.28e-4.
- 6 In the y text field, type 55.38e-4.

7 In the z text field, type 10e-4.

Union I (uni I)

- I In the Geometry toolbar, click 📕 Booleans and Partitions and choose Union.
- 2 Click the **Select All** button in the **Graphics** toolbar and remove the cylinder from the selection.

Intersection 1 (int1)

- I In the Geometry toolbar, click 💻 Booleans and Partitions and choose Intersection.
- 2 Click in the Graphics window and then press Ctrl+A to select both objects.

Work Plane I (wp1)

- I In the Geometry toolbar, click 📥 Work Plane.
- **2** Click the **Com Extents** button in the **Graphics** toolbar.
- 3 In the Settings window for Work Plane, locate the Plane Definition section.
- 4 In the z-coordinate text field, type 13.5e-4.

Work Plane 2 (wp2)

- I Right-click Work Plane I (wpl) and choose Duplicate.
- 2 In the Settings window for Work Plane, locate the Plane Definition section.
- 3 In the z-coordinate text field, type 15.5e-4.

Partition Objects 1 (parl)

- I In the Geometry toolbar, click 📕 Booleans and Partitions and choose Partition Objects.
- 2 In the Settings window for Partition Objects, locate the Partition Objects section.
- **3** From the **Partition with** list, choose **Work plane**.
- 4 From the Work plane list, choose Work Plane I (wpl).
- 5 From the **Repair tolerance** list, choose **Relative**.
- 6 In the Relative repair tolerance text field, type 3E-4.
- 7 Select the object intl only.

Partition Objects 2 (par2)

- I In the Geometry toolbar, click 📕 Booleans and Partitions and choose Partition Objects.
- 2 Select the object **par1** only.
- 3 In the Settings window for Partition Objects, locate the Partition Objects section.
- 4 From the Partition with list, choose Work plane.
- 5 Click 📗 Build All Objects.

6 Click the 🕂 Zoom Extents button in the Graphics toolbar.

GEOMETRY 2

In the Model Builder window, collapse the Submodel (comp2)>Geometry 2 node.

ADD PHYSICS

- I In the Home toolbar, click 🙀 Add Physics to open the Add Physics window.
- 2 Go to the Add Physics window.
- 3 In the tree, select Structural Mechanics>Thermal-Structure Interaction>Thermal Stress, Solid.
- **4** Find the **Physics interfaces in study** subsection. In the table, clear the **Solve** check boxes for **Full Model: Load History** and **Full Model: Fatigue Evaluation**.
- 5 Click Add to Submodel in the window toolbar.
- 6 In the Home toolbar, click 🙀 Add Physics to close the Add Physics window.

SOLID MECHANICS 2 (SOLID2)

- I In the Settings window for Solid Mechanics, locate the Structural Transient Behavior section.
- 2 From the list, choose Quasistatic.

Linear Elastic Material I

- I Click the 😇 Show More Options button in the Model Builder toolbar.
- 2 In the Show More Options dialog box, in the tree, select the check box for the node Physics>Advanced Physics Options.
- 3 Click OK.
- 4 In the Model Builder window, under Submodel (comp2)>Solid Mechanics 2 (solid2) click Linear Elastic Material I.
- **5** In the **Settings** window for **Linear Elastic Material**, click to expand the **Energy Dissipation** section.
- 6 Select the Calculate dissipated energy check box.

Viscoplasticity 1

- I In the Physics toolbar, click 层 Attributes and choose Viscoplasticity.
- 2 In the Settings window for Viscoplasticity, locate the Domain Selection section.
- 3 Click Clear Selection.
- **4** Select Domains 4–6 only.

Prescribe results of the structural analysis via displacements on the shared boundaries.

Prescribed Displacement I

- I In the Physics toolbar, click 🕞 Boundaries and choose Prescribed Displacement.
- **2** Select Boundaries 1–5, 8, 9, 11, and 22–27 only.
- **3** In the **Settings** window for **Prescribed Displacement**, locate the **Prescribed Displacement** section.
- 4 Select the Prescribed in x direction check box.
- **5** In the u_{0x} text field, type compl.genext1(compl.u).
- 6 Select the Prescribed in y direction check box.
- 7 In the u_{0v} text field, type compl.genext1(compl.v).
- 8 Select the Prescribed in z direction check box.
- **9** In the u_{0z} text field, type compl.genext1(compl.w).
- **10** Click to expand the **Constraint Settings** section. From the **Apply reaction terms on** list, choose **Current physics (internally symmetric)**.

HEAT TRANSFER IN SOLIDS 2 (HT2)

In the Model Builder window, under Submodel (comp2) click Heat Transfer in Solids 2 (ht2).

Heat Source 1

- I In the Physics toolbar, click 🔚 Domains and choose Heat Source.
- **2** Select Domain 3 only.
- 3 In the Settings window for Heat Source, locate the Heat Source section.
- **4** In the Q_0 text field, type power(t).

Heat Flux 1

- I In the Physics toolbar, click 🔚 Boundaries and choose Heat Flux.
- **2** Select Boundaries 7, 10, 12–15, 17, and 18 only.
- 3 In the Settings window for Heat Flux, locate the Heat Flux section.
- 4 From the Flux type list, choose Convective heat flux.
- **5** In the h text field, type 10.
- **6** In the T_{ext} text field, type T0.

Prescribe results of the heat transfer analysis via temperature on the shared boundaries.

Temperature 1

I In the Physics toolbar, click 📄 Boundaries and choose Temperature.

- **2** Select Boundaries 1–5, 8, 9, 11, and 22–27 only.
- 3 In the Settings window for Temperature, locate the Temperature section.
- **4** In the T_0 text field, type compl.genext1(compl.T).

MATERIALS

Material Link 5 (matlnk5)

- I In the Model Builder window, under Submodel (comp2) right-click Materials and choose More Materials>Material Link.
- **2** Select Domain 1 only.

Material Link 6 (matlnk6)

- I Right-click Materials and choose More Materials>Material Link.
- **2** Select Domain 2 only.
- 3 In the Settings window for Material Link, locate the Link Settings section.
- 4 From the Material list, choose Copper (mat2).

Material Link 7 (matlnk7)

- I Right-click Materials and choose More Materials>Material Link.
- **2** Select Domain 3 only.
- 3 In the Settings window for Material Link, locate the Link Settings section.
- 4 From the Material list, choose Silicon (mat3).

Material Link 8 (matlnk8)

- I Right-click Materials and choose More Materials>Material Link.
- **2** Select Domains 4–6 only.
- 3 In the Settings window for Material Link, locate the Link Settings section.
- 4 From the Material list, choose Solder, 60Sn-40Pb (mat4).

Refine the mesh in the solder ball.

MESH 2

- I In the Model Builder window, under Submodel (comp2) click Mesh 2.
- 2 In the Settings window for Mesh, locate the Sequence Type section.
- **3** From the list, choose **User-controlled mesh**.

Size 1

I In the Model Builder window, right-click Free Tetrahedral I and choose Size.

- 2 In the Settings window for Size, locate the Geometric Entity Selection section.
- 3 From the Geometric entity level list, choose Domain.
- **4** Select Domains 4–6 only.
- 5 Locate the Element Size section. From the Predefined list, choose Fine.
- 6 Click 📗 Build All.

Simulate the initial cycles using the submodel.

ADD STUDY

- I In the Home toolbar, click $\stackrel{\text{reg}}{\longrightarrow}$ Add Study to open the Add Study window.
- 2 Go to the Add Study window.
- **3** Find the **Physics interfaces in study** subsection. In the table, clear the **Solve** check boxes for **Solid Mechanics (solid)**, **Heat Transfer in Solids (ht)**, and **Fatigue (ftg)**.
- 4 Find the Studies subsection. In the Select Study tree, select General Studies> Time Dependent.
- 5 Click Add Study in the window toolbar.
- 6 In the Model Builder window, click the root node.
- 7 In the Home toolbar, click ~ 2 Add Study to close the Add Study window.

SUBMODEL: LOAD HISTORY

In the Settings window for Study, type Submodel: Load History in the Label text field.

Step 1: Time Dependent

Store data mainly for the thermal cycle where we want to perform the fatigue evaluation.

- I In the Model Builder window, under Submodel: Load History click Step I: Time Dependent.
- 2 In the Settings window for Time Dependent, locate the Study Settings section.
- 3 From the Time unit list, choose h.
- 4 In the Output times text field, type 0 range(1,1,17) 18+{range(0,0.025,0.5) range(0.75,0.25,3.75) 3.95 4+{range(0.025,0.025,0.5) range(0.75,0.25, 2)}.
- 5 Click to expand the Values of Dependent Variables section. Find the Values of variables not solved for subsection. From the Settings list, choose User controlled.
- 6 From the Method list, choose Solution.
- 7 From the Study list, choose Full Model: Load History, Time Dependent 2.

8 From the Time (h) list, choose Automatic (all solutions).

Set up the solver in a similar way as in **Study I**.

Solution 4 (sol4)

- I In the Study toolbar, click The Show Default Solver.
- 2 In the Model Builder window, expand the Solution 4 (sol4) node.
- 3 In the Model Builder window, expand the Submodel: Load History>Solver Configurations> Solution 4 (sol4)>Dependent Variables 1 node, then click Viscoplastic dissipation density (comp2.solid2.Wvp).
- 4 In the Settings window for Field, locate the Scaling section.
- 5 From the Method list, choose Manual.
- 6 In the Scale text field, type 1e5.
- 7 In the Model Builder window, under Submodel: Load History>Solver Configurations> Solution 4 (sol4) click Time-Dependent Solver 1.
- 8 In the Settings window for Time-Dependent Solver, click to expand the Time Stepping section.
- 9 From the Steps taken by solver list, choose Strict.
- **IO** Click to expand the **Output** section. Clear the **Store time derivatives** check box.
- II In the Model Builder window, expand the Submodel: Load History>Solver Configurations> Solution 4 (sol4)>Time-Dependent Solver I node, then click Segregated I.
- 12 In the Settings window for Segregated, locate the General section.
- **I3** From the **Termination technique** list, choose **Iterations**.
- I4 In the Model Builder window, expand the Submodel: Load History>Solver Configurations> Solution 4 (sol4)>Time-Dependent Solver I>Segregated I node, then click Temperature.
- **IS** In the **Settings** window for **Segregated Step**, click to expand the **Method and Termination** section.
- **I6** From the **Termination technique** list, choose **Tolerance**.
- **I7** In the **Tolerance factor** text field, type 1.
- 18 In the Model Builder window, under Submodel: Load History>Solver Configurations> Solution 4 (sol4)>Time-Dependent Solver I>Segregated I click Solid Mechanics 2.
- 19 In the Settings window for Segregated Step, locate the Method and Termination section.
- **20** From the Nonlinear method list, choose Constant (Newton).
- 21 From the Termination technique list, choose Tolerance.

- 22 In the Maximum number of iterations text field, type 20.
- **2** Locate the **General** section. In the **Variables** list, select

Viscoplastic dissipation density (comp2.solid2.Wvp).

- 24 Under Variables, click 🗮 Delete.
- 25 In the Model Builder window, under Submodel: Load History>Solver Configurations> Solution 4 (sol4)>Time-Dependent Solver I right-click Segregated I and choose Segregated Step.
- 26 Drag and drop Submodel: Load History

```
Solver Configurations
Solution 4 (sol4)
Time-Dependent Solver I
Segregated I
Segregated Step 3 below Solid Mechanics 2.
```

- **27** In the Settings window for Segregated Step, locate the General section.
- **28** Under **Variables**, click + **Add**.
- **29** In the Add dialog box, select Viscoplastic dissipation density (comp2.solid2.Wvp) in the Variables list.
- 30 Click OK.
- **3I** In the **Settings** window for **Segregated Step**, type Energy Dissipation in the **Label** text field.
- **32** Locate the **Method and Termination** section. From the **Termination technique** list, choose **Tolerance**.
- 33 In the Tolerance factor text field, type 1.
- **34** In the **Study** toolbar, click **= Compute**.

RESULTS

```
Stress (solid2)
```

Simulate the fatigue load cycle on the submodel and evaluate fatigue response of the critical solder joint.

SUBMODEL (COMP2)

In the Model Builder window, click Submodel (comp2).

ADD PHYSICS

I In the Home toolbar, click 🙀 Add Physics to open the Add Physics window.

- 2 Go to the Add Physics window.
- 3 In the tree, select Structural Mechanics>Fatigue (ftg).
- 4 Find the Physics interfaces in study subsection. In the table, clear the Solve check boxes for Full Model: Load History, Full Model: Fatigue Evaluation, and Submodel: Load History.
- 5 Click Add to Submodel in the window toolbar.
- 6 In the Home toolbar, click 🙀 Add Physics to close the Add Physics window.

FATIGUE 2 (FTG2)

Energy-Based I

- I Right-click Submodel (comp2)>Fatigue 2 (ftg2) and choose the domain evaluation Energy-Based.
- **2** Select Domains 4–6 only.
- 3 In the Settings window for Energy-Based, locate the Solution Field section.
- 4 From the Physics interface list, choose Solid Mechanics 2 (solid2).
- 5 Locate the Fatigue Model Selection section. From the Criterion list, choose Darveaux.
- 6 From the Energy type list, choose Viscoplastic dissipation density.
- 7 Locate the Evaluation Settings section. From the Volume average method list, choose Entire selection.
- 8 Locate the Fatigue Model Parameters section. In the *a* text field, type lorack.

ADD PHYSICS

- I In the Physics toolbar, click 🙀 Add Physics to open the Add Physics window.
- 2 Go to the Add Physics window.
- 3 In the tree, select Recently Used>Fatigue (ftg).
- 4 Find the Physics interfaces in study subsection. In the table, clear the Solve check boxes for Full Model: Load History, Full Model: Fatigue Evaluation, and Submodel: Load History.
- 5 Click Add to Submodel in the window toolbar.
- 6 In the Physics toolbar, click 🙀 Add Physics to close the Add Physics window.

FATIGUE 3 (FTG3)

Right-click Submodel (comp2)>Fatigue 3 (ftg3) and choose the domain evaluation Energy-Based.

Energy-Based I

I Select Domains 4–6 only.

- 2 In the Settings window for Energy-Based, locate the Solution Field section.
- 3 From the Physics interface list, choose Solid Mechanics 2 (solid2).
- 4 Locate the Fatigue Model Selection section. From the Criterion list, choose Darveaux.
- 5 From the Energy type list, choose Viscoplastic dissipation density.
- 6 Locate the Fatigue Model Parameters section. In the *a* text field, type lcrack.

ADD STUDY

- I In the Home toolbar, click $\sim\sim$ Add Study to open the Add Study window.
- 2 Go to the Add Study window.
- 3 Find the Physics interfaces in study subsection. In the table, clear the Solve check boxes for Solid Mechanics (solid), Heat Transfer in Solids (ht), Fatigue (ftg), Solid Mechanics 2 (solid2), and Heat Transfer in Solids 2 (ht2).
- 4 Find the Studies subsection. In the Select Study tree, select Preset Studies for Selected Physics Interfaces>Fatigue.
- 5 Click Add Study in the window toolbar.
- 6 In the Home toolbar, click $\stackrel{\text{res}}{\longrightarrow}$ Add Study to close the Add Study window.

SUBMODEL: FATIGUE EVALUATION

- I In the Model Builder window, click Study 4.
- 2 In the Settings window for Study, type Submodel: Fatigue Evaluation in the Label text field.

Step 1: Fatigue

- I In the Model Builder window, under Submodel: Fatigue Evaluation click Step I: Fatigue.
- 2 In the Settings window for Fatigue, locate the Values of Dependent Variables section.
- **3** Find the **Values of variables not solved for** subsection. From the **Settings** list, choose **User controlled**.
- 4 From the Method list, choose Solution.
- 5 From the Study list, choose Submodel: Load History, Time Dependent.
- 6 From the Time (h) list, choose From list.
- 7 From the list, select time steps from 18h to 24h.
- 8 In the **Home** toolbar, click **= Compute**.

RESULTS

Temperature (ht2)

Compare the viscoplastic dissipation in the full model and in the submodel.

Dissipation History

- I In the Model Builder window, click Dissipation History.
- 2 In the Settings window for ID Plot Group, click to expand the Title section.
- **3** From the **Title type** list, choose **None**.
- 4 Locate the Legend section. From the Position list, choose Upper left.

Point Graph 1

- I In the Model Builder window, expand the Dissipation History node, then click Point Graph I.
- 2 In the Settings window for Point Graph, click to expand the Legends section.
- 3 Select the Show legends check box.
- 4 From the Legends list, choose Manual.
- **5** In the table, enter the following settings:

Legends

Full model

Point Graph 2

- I Right-click Results>Dissipation History>Point Graph I and choose Duplicate.
- 2 In the Settings window for Point Graph, locate the y-Axis Data section.
- **3** In the **Expression** text field, type solid2.WvpGp.
- **4** In the **Unit** field, type kJ/m³.
- 5 Locate the Data section. From the Dataset list, choose Submodel: Load History/ Solution 4 (5) (sol4).
- 6 Locate the Selection section. Click to select the 🔲 Activate Selection toggle button.
- **7** Select Point 9 only.
- 8 Click to expand the **Coloring and Style** section. Find the **Line markers** subsection. From the **Marker** list, choose **Circle**.
- 9 Locate the Legends section. In the table, enter the following settings:

Legends

Submodel

Shear Viscoplasticity History

- I In the Model Builder window, right-click Dissipation History and choose Duplicate.
- 2 In the Settings window for ID Plot Group, type Shear Viscoplasticity History in the Label text field.
- 3 Locate the Plot Settings section.
- **4** Select the **y-axis label** check box. In the associated text field, type Shear viscoplasticity.
- 5 Locate the Legend section. From the Position list, choose Lower left.

Point Graph 1

- I In the Model Builder window, expand the Shear Viscoplasticity History node, then click Point Graph I.
- 2 In the Settings window for Point Graph, click Replace Expression in the upper-right corner of the y-Axis Data section. From the menu, choose Full Model (compl)> Solid Mechanics>Strain (Gauss points)>Viscoplastic strain tensor, local coordinate system> solid.evplGp13 Viscoplastic strain tensor, local coordinate system, 13-component.

Point Graph 2

- I In the Model Builder window, click Point Graph 2.
- In the Settings window for Point Graph, click Replace Expression in the upper-right corner of the y-Axis Data section. From the menu, choose Submodel (comp2)>
 Solid Mechanics 2>Strain (Gauss points)>Viscoplastic strain tensor, local coordinate system>solid2.evplGp13 Viscoplastic strain tensor, local coordinate system, 13-component.
- 3 In the Shear Viscoplasticity History toolbar, click 💿 Plot.

Verify that the temperature is the same in both studies.

Temperature History

- I In the Model Builder window, under Results click Temperature History.
- 2 In the Settings window for ID Plot Group, locate the Title section.
- **3** From the **Title type** list, choose **None**.
- 4 Locate the **Plot Settings** section.
- 5 Select the y-axis label check box. In the associated text field, type Temperature (C).
- 6 Locate the Legend section. From the Position list, choose Upper left.

Point Graph 1

- I In the Model Builder window, expand the Temperature History node, then click Point Graph I.
- 2 In the Settings window for Point Graph, locate the Legends section.
- 3 Select the Show legends check box.
- 4 From the Legends list, choose Manual.
- **5** In the table, enter the following settings:

Legends

Full model

Point Graph 2

- I Right-click Results>Temperature History>Point Graph I and choose Duplicate.
- 2 In the Settings window for Point Graph, locate the y-Axis Data section.
- **3** In the **Expression** text field, type T2.
- 4 In the **Unit** field, type degC.
- 5 Locate the Data section. From the Dataset list, choose Submodel: Load History/ Solution 4 (5) (sol4).
- 6 Locate the Selection section. Click to select the 🔲 Activate Selection toggle button.
- 7 Select Point 9 only.
- 8 Locate the Coloring and Style section. Find the Line style subsection. From the Line list, choose None.
- 9 Find the Line markers subsection. From the Marker list, choose Circle.
- **IO** Locate the **Legends** section. In the table, enter the following settings:

Legends

Submodel

Display the minimum cycles to failure for each solution.

Cycles to Failure (ftg)

In the Model Builder window, expand the Cycles to Failure (ftg) node.

Marker I

- I In the Model Builder window, expand the Results>Cycles to Failure (ftg)>Surface I node, then click Marker I.
- 2 In the Settings window for Marker, locate the Text Format section.

3 In the **Display precision** text field, type **2**.

Cycles to Failure (ftg2)

In the Model Builder window, expand the Cycles to Failure (ftg2) node.

Marker I

- I In the Model Builder window, expand the Results>Cycles to Failure (ftg2)>Surface I node, then click Marker I.
- 2 In the Settings window for Marker, locate the Text Format section.
- 3 In the Display precision text field, type 2.

Cycles to Failure (ftg3)

In the Model Builder window, expand the Cycles to Failure (ftg3) node.

Marker I

- I In the Model Builder window, expand the Results>Cycles to Failure (ftg3)>Surface I node, then click Marker I.
- 2 In the Settings window for Marker, locate the Text Format section.
- **3** In the **Display precision** text field, type **1**.

Evaluation Group 1

In the **Results** toolbar, click **Levaluation Group**.

Volume Minimum I

- I Right-click Evaluation Group I and choose Volume Minimum.
- 2 In the Settings window for Volume Minimum, locate the Data section.
- 3 From the Dataset list, choose Full Model: Fatigue Evaluation/Solution 3 (sol3).
- 4 Locate the Selection section. From the Selection list, choose Solder.
- 5 Click Replace Expression in the upper-right corner of the Expressions section. From the menu, choose Full Model (compl)>Fatigue>ftg.ctf Cycles to failure.

Evaluation Group 1

In the Model Builder window, click Evaluation Group I.

Volume Minimum 2

- I In the Evaluation Group I toolbar, click MIN Minimum and choose Volume Minimum.
- 2 In the Settings window for Volume Minimum, locate the Data section.
- 3 From the Dataset list, choose Submodel: Fatigue Evaluation/Solution 5 (7) (sol5).
- **4** Select Domains 4–6 only.

5 Locate the **Expressions** section. In the table, enter the following settings:

Expression	Unit	Description
ftg2.ctf	1	Cycles to failure, submodel
ftg3.ctf	1	Cycles to failure, thin layer in submodel

6 In the Evaluation Group I toolbar, click = Evaluate.