

Deformation of an Iron Plate by Magnetic Force

Introduction

A strong permanent magnet is placed close to a clamped thin plate made of iron. The magnetic force causes the plate to be deflected. This example studies the elastic deformation and stress of the plate. The deformation of the plate has an influence on the distribution of the magnetic field. This effect is accounted for using a moving mesh in the air surrounding the plate. The model is set up using the Magnetomechanics, No Currents multiphysics interface.

Model Definition

The geometry consists of a permanent magnet and a metal plate surrounded by air.





The plate is elastic and made of soft iron with the nonlinear magnetization properties specified as the BH curve shown in Figure 3. The plate initial thickness is 1 mm. Two shorter side boundaries of the plate are fixed and all the other boundaries are free.

The magnet consists of two rectangular N35 magnets connected by a curved piece of iron as shown in Figure 1. The magnet is fixed in space and is not part of the structural analysis.

Because of the symmetry, you can model only one quarter of the magnet and plate. In addition, the magnetic field needs to be computed in the surrounding air using a bounding box shown in Figure 2



Figure 2: Model geometry.

To include the effect of the change of the distance when the plate is deflected by the magnetic field, you set up a moving mesh in a thin layer surrounding the plate, as can be seen in Figure 2. The mesh is free to deform inside the layer, and it can slide on the symmetry cut boundaries.

For the structural problem and the moving mesh, symmetry conditions are used at both symmetry cut planes. However, the magnetic problem needs a symmetry condition on one of the cut planes (on the left in Figure 2) and an antisymmetry condition on the other one (on the right in Figure 2).



Figure 3: BH curve for soft iron.

Results and Discussion

The magnetic field and plate displacement have been computed for several values of the initial distance, dm, between the plate and the magnet poles.

The computation results are visualized for dm = 3 mm for the full geometry in Figure 4– Figure 7 by using mirror datasets.

Figure 4 shows that the stress level in the deformed plate is moderate, and it is far below the yield strengths of the material. Figure 6 and Figure 7 show that the magnetic flux density can reach quite significant values, so that certain parts of the plate will be in a magnetization state near the material saturation.



Figure 4: Stress distribution in the plate for the initial distance of 3 mm to the magnet.



Figure 5: Displacement of the plate for the initial distance of 3 mm to the magnet.



Figure 6: Magnetic flux density for the initial distance of 3 mm between the plate and magnet.



Figure 7: Magnetic flux density and magnetic flux streamlines in a slice parallel to the plate upper surface for the initial distance of 3 mm between the plate and magnet.

Figure 8 shows that the relative deflection of the plate can be significant, which justifies the need to use the moving mesh when computing the magnetic field in the surrounding air.



Figure 8: Maximum displacement of the plate in percent of the initial distance between the plate and the magnet poles.

Figure 9 shows very good agreement between the total magnetic pulling force and the total structural reaction force for all studied values of the initial distance between the plate and the magnet poles.



Figure 9: The total pulling magnetic force and the total structural reaction force (recomputed for the full geometry).

Notes About the COMSOL Implementation

The model is set up using the Magnetomechanics, No Currents multiphysics interface. When this interface is added to a model, one Solid Mechanics and one Magnetic Fields, No Currents physics interface are added automatically together with a Magnetic Forces multiphysics coupling feature. Two moving-mesh-related nodes are also added automatically: a Deforming Domain and a Symmetry/Roller boundary condition.

The magnetic body and surface forces acting on the plate are applied automatically by the coupling feature on its selection. Later on in the modeling, you will also add a Force Calculation node under the Magnetic Fields, No Currents physics interface. The node is only used in postprocessing for computing the total force acting on the plate.

Application Library path: ACDC_Module/Electromagnetics_and_Mechanics/
plate_deflected_by_magnet

Modeling Instructions

From the File menu, choose New.

NEW

In the New window, click 🔗 Model Wizard.

MODEL WIZARD

- I In the Model Wizard window, click 间 3D.
- 2 In the Select Physics tree, select Structural Mechanics>Electromagnetics-Structure Interaction>Magnetomechanics>Magnetomechanics, No Currents.
- 3 Click Add.
- 4 Click 🔿 Study.
- 5 In the Select Study tree, select General Studies>Stationary.
- 6 Click **M** Done.

GLOBAL DEFINITIONS

Parameters, geometry

- I In the Model Builder window, under Global Definitions click Parameters I.
- 2 In the Settings window for Parameters, type Parameters, geometry in the Label text field.
- 3 Locate the Parameters section. In the table, enter the following settings:

Name	Expression	Value	Description
dm	3[mm]	0.003 m	Distance to magnet
hp	1 [mm]	0.001 m	Plate thickness
lp	20[cm]	0.2 m	Plate length
wp	6[cm]	0.06 m	Plate width
Н	7[cm]	0.07 m	Distance to bottom wall

GEOMETRY I

- Work Plane I (wp1)
- I In the Geometry toolbar, click Work Plane.

Use the work plane to set up one quarter of the magnet geometry.

2 In the Settings window for Work Plane, locate the Plane Definition section.

- 3 From the Plane list, choose zy-plane.
- 4 In the **x-coordinate** text field, type 0.01.

Work Plane I (wpI)>Plane Geometry

In the Model Builder window, click Plane Geometry.

Work Plane I (wpI)>Circle I (cI)

- I In the Work Plane toolbar, click 📀 Circle.
- 2 In the Settings window for Circle, locate the Size and Shape section.
- 3 In the Radius text field, type 0.04.
- 4 In the Sector angle text field, type 90.
- 5 Locate the **Position** section. In the **xw** text field, type 0.06.

Work Plane I (wpI)>Circle 2 (c2)

- I Right-click Component I (comp1)>Geometry I>Work Plane I (wp1)>Plane Geometry> Circle I (c1) and choose Duplicate.
- 2 In the Settings window for Circle, locate the Size and Shape section.
- 3 In the Radius text field, type 0.02.

Work Plane I (wp1)>Difference I (dif1)

- I In the Work Plane toolbar, click 📁 Booleans and Partitions and choose Difference.
- 2 Select the object **cl** only.
- 3 In the Settings window for Difference, locate the Difference section.
- **4** Find the **Objects to subtract** subsection. Click to select the **Delta Activate Selection** toggle button.
- **5** Select the object **c2** only.

Work Plane I (wp1)>Rectangle I (r1)

- I In the Work Plane toolbar, click Rectangle.
- 2 In the Settings window for Rectangle, locate the Size and Shape section.
- **3** In the **Width** text field, type 0.05.
- 4 In the **Height** text field, type 0.02.
- **5** Locate the **Position** section. In the **yw** text field, type **0.02**.

Work Plane I (wp1)>Rectangle 2 (r2)

I Right-click Component I (comp1)>Geometry I>Work Plane I (wp1)>Plane Geometry> Rectangle I (r1) and choose Duplicate.

- 2 In the Settings window for Rectangle, locate the Size and Shape section.
- **3** In the **Width** text field, type 0.01.
- **4** Locate the **Position** section. In the **xw** text field, type **0.05**.
- 5 Click 틤 Build Selected.

Extrude I (extI)

- In the Model Builder window, under Component I (compl)>Geometry I right-click
 Work Plane I (wpl) and choose Extrude.
- 2 In the Settings window for Extrude, locate the Distances section.
- **3** In the table, enter the following settings:

Distances (m)

0.01

Add a block representing one quarter of the plate.

Block I (blkI)

- I In the **Geometry** toolbar, click 🗍 **Block**.
- 2 In the Settings window for Block, locate the Size and Shape section.
- **3** In the **Width** text field, type wp/2.
- 4 In the **Depth** text field, type 1p/2.
- 5 In the **Height** text field, type hp.
- 6 Locate the **Position** section. In the **z** text field, type (dm+hp).

Finally, set up a bounding box for the geometry, which will define the surrounding air domains.

Block 2 (blk2)

- I In the **Geometry** toolbar, click 🗍 **Block**.
- 2 In the Settings window for Block, locate the Size and Shape section.
- 3 In the Width text field, type 2*wp.
- 4 In the **Depth** text field, type 1p/2+wp.
- 5 In the **Height** text field, type 0.2.
- 6 Locate the Position section. In the z text field, type -H.
- 7 Click to expand the Layers section. Specify two layers to define the domain, where a moving mesh will be used.

8 In the table, enter the following settings:

Layer name	Thickness (m)
Layer 1	H-2*dm-hp
Layer 2	2*dm+hp

9 Click 🟢 Build All Objects.

IO Click the Transparency button in the Graphics toolbar.



ADD MATERIAL

- I In the Home toolbar, click 🙀 Add Material to open the Add Material window.
- 2 Go to the Add Material window.

Add the plate and magnet materials.

- 3 In the tree, select AC/DC>Soft Iron (Without Losses).
- 4 Right-click and choose Add to Component I (compl).
- 5 In the tree, select AC/DC>Hard Magnetic Materials> Sintered NdFeB Grades (Chinese Standard)>N35 (Sintered NdFeB).
- 6 Right-click and choose Add to Component I (compl).

MATERIALS

- N35 (Sintered NdFeB) (mat2)
- I In the Model Builder window, under Component I (compl)>Materials click N35 (Sintered NdFeB) (mat2).
- **2** Select Domain 6 only.

Use air in the surrounding domains.

ADD MATERIAL

- I Go to the Add Material window.
- 2 In the tree, select Built-in>Air.
- 3 Right-click and choose Add to Component I (compl).
- 4 In the Home toolbar, click 🙀 Add Material to close the Add Material window.

MATERIALS

Air (mat3) Select Domains 1, 2, and 4 only.

Set up moving mesh in the air domain surrounding the plate.

MOVING MESH

Deforming Domain 1

- I In the Model Builder window, under Component I (compl)>Moving Mesh click Deforming Domain I.
- **2** Select Domain 2 only.

Allow the mesh to slide on the boundaries representing the symmetry cuts.

Symmetry/Roller 1

- I In the Model Builder window, click Symmetry/Roller I.
- **2** Select Boundaries 4 and 5 only.

Perform the structural analysis only in the domain representing the plate.

SOLID MECHANICS (SOLID)

- I In the Model Builder window, under Component I (compl) click Solid Mechanics (solid).
- 2 Select Domain 3 only.

Fixed Constraint I

I In the Physics toolbar, click 🔚 Boundaries and choose Fixed Constraint.

One side boundary of the plate is fixed.

2 Select Boundary 29 only.

Two external side boundaries represent the symmetry cuts.

Symmetry I

- I In the Physics toolbar, click 📄 Boundaries and choose Symmetry.
- **2** Select Boundaries 7 and 8 only.

MAGNETIC FIELDS, NO CURRENTS (MFNC)

Magnetic Flux Conservation, Solid

The plate and the curved part connecting the magnet poles are made of iron that has nonlinear magnetization properties, including possible saturation.

- In the Model Builder window, under Component I (compl)>Magnetic Fields, No Currents (mfnc) click Magnetic Flux Conservation, Solid.
- 2 In the Settings window for Magnetic Flux Conservation, locate the Constitutive Relation B-H section.
- **3** From the Magnetization model list, choose **B-H curve**.

Magnetic Flux Conservation, Magnet

- I In the **Physics** toolbar, click **Domains** and choose **Magnetic Flux Conservation**. You model the magnet using the remanent flux density defined by the material.
- 2 In the Settings window for Magnetic Flux Conservation, type Magnetic Flux Conservation, Magnet in the Label text field.
- **3** Select Domain 6 only.
- 4 Locate the Material Type section. From the Material type list, choose Solid.
- 5 Locate the Constitutive Relation B-H section. From the Magnetization model list, choose Remanent flux density.
- **6** Specify the **e** vector as

0	х
0	Y
1	z

Set up the nonsolid domains representing the air.

Magnetic Flux Conservation, Air

- I In the Physics toolbar, click 🔚 Domains and choose Magnetic Flux Conservation.
- 2 In the Settings window for Magnetic Flux Conservation, type Magnetic Flux Conservation, Air in the Label text field.
- **3** Select Domains 1, 2, and 4 only.

Next, define the conditions on the boundaries representing the symmetry cuts. Note that two different types of conditions are needed.

Symmetry Plane, Symmetry

- I In the Physics toolbar, click 🔚 Boundaries and choose Symmetry Plane.
- 2 In the Settings window for Symmetry Plane, type Symmetry Plane, Symmetry in the Label text field.
- 3 Locate the Boundary Selection section. Click 📄 Paste Selection.
- 4 In the Paste Selection dialog box, type 1, 4, 7, 11, 14, 17, 20, 23 in the Selection text field.
- 5 Click OK.





- 2 In the Settings window for Symmetry Plane, type Symmetry Plane, Antisymmetry in the Label text field.
- **3** Locate the Symmetry Plane section. From the Symmetry type for the magnetic field list, choose Antisymmetry.
- 4 Locate the Boundary Selection section. Click 📄 Paste Selection.
- 5 In the Paste Selection dialog box, type 2, 5, 8, 12, 15 in the Selection text field.
- 6 Click OK.



MATERIALS

Soft Iron (Without Losses) (mat1)

- I In the Model Builder window, under Component I (compl)>Materials click Soft Iron (Without Losses) (matl).
- 2 In the Settings window for Material, locate the Material Contents section.

3 In the table, enter the following settings:

Property	Variable	Value	Unit	Property group
Young's modulus	E	200[GPa]	Pa	Young's modulus and Poisson's ratio
Poisson's ratio	nu	0.29	I	Young's modulus and Poisson's ratio
Density	rho	7870[kg/m^3]	kg/m³	Basic

Define a few parameters to control the meshing of the geometry.

GLOBAL DEFINITIONS

Parameters, accuracy

- I In the Home toolbar, click Pi Parameters and choose Add>Parameters.
- **2** In the **Settings** window for **Parameters**, type **Parameters**, accuracy in the **Label** text field.
- 3 Locate the **Parameters** section. In the table, enter the following settings:

Name	Expression	Value	Description
ар	0	0	Accuracy parameter: 0 - normal, 1 - high
hmax1	5[mm]-2.6[mm]*ap	0.005 m	Meshing parameter
hmax2	20[mm]-10[mm]*ap	0.02 m	Meshing parameter

Use swept meshes in the domains representing the plate and magnet. Start by meshing two respective adjacent surfaces.

MESH I

Free Triangular 1

- I In the Mesh toolbar, click \bigwedge Boundary and choose Free Triangular.
- 2 In the Settings window for Free Triangular, locate the Boundary Selection section.
- 3 Click Paste Selection.
- 4 In the Paste Selection dialog box, type 10, 22 in the Selection text field.

5 Click OK.



Size 1

- I Right-click Free Triangular I and choose Size.
- 2 In the Settings window for Size, locate the Element Size section.
- 3 Click the **Custom** button.
- 4 Locate the Element Size Parameters section.
- 5 Select the Maximum element size check box. In the associated text field, type hmax1.

Swept I

- I In the Mesh toolbar, click A Swept.
- 2 In the Settings window for Swept, locate the Domain Selection section.
- **3** From the **Geometric entity level** list, choose **Domain**.
- 4 Click **Paste Selection**.
- 5 In the Paste Selection dialog box, type 5-7 in the Selection text field.

6 Click OK.



Distribution I

- I Right-click Swept I and choose Distribution.
- 2 In the Settings window for Distribution, locate the Domain Selection section.
- **3** In the list, select **7**.
- **4** Click Remove from Selection.
- **5** Select Domains 5 and 6 only.
- 6 Locate the Distribution section. In the Number of elements text field, type 10.

Distribution 2

- I In the Model Builder window, right-click Swept I and choose Distribution.
- **2** Select Domain 7 only.
- 3 In the Settings window for Distribution, locate the Distribution section.
- 4 In the Number of elements text field, type 2.

Swept 2

- I In the Mesh toolbar, click 🦓 Swept.
- 2 In the Settings window for Swept, locate the Domain Selection section.

- 3 From the Geometric entity level list, choose Domain.
- **4** Select Domain 2 only.
- **5** Click **Remove from Selection**.
- 6 Select Domains 2 and 3 only.
- 7 In the list, select 2.
- 8 Click Remove from Selection.
- **9** Select Domain 3 only.

Distribution I

- I Right-click Swept 2 and choose Distribution.
- 2 In the Settings window for Distribution, locate the Distribution section.
- 3 In the Number of elements text field, type 3.

Mesh the rest of the geometry using a free tetrahedral mesh.

Free Tetrahedral I

In the Mesh toolbar, click \land Free Tetrahedral.

Size 1

- I Right-click Free Tetrahedral I and choose Size.
- 2 In the Settings window for Size, locate the Element Size section.
- 3 Click the **Custom** button.
- 4 Locate the Element Size Parameters section.
- 5 Select the Maximum element size check box. In the associated text field, type hmax2.

6 Click 🏢 Build All.



Set up a parametric sweep to study cases of several different distances between the plate and magnet.

STUDY I

Parametric Sweep

- I In the Study toolbar, click **Parametric Sweep**.
- 2 In the Settings window for Parametric Sweep, locate the Study Settings section.
- 3 Click + Add.
- **4** In the table, enter the following settings:

Parameter name	Parameter value list	Parameter unit
dm (Distance to magnet)	7543	mm

Modify the default solver to reduce the solving time and to improve the numerical stability.

Solution I (soll)

- I In the Study toolbar, click **Show Default Solver**.
- 2 In the Model Builder window, expand the Solution I (soll) node.

- 3 In the Model Builder window, expand the Study I>Solver Configurations>
 Solution I (soll)>Stationary Solver I>Segregated I node, then click Magnetic potential.
- 4 In the Settings window for Segregated Step, locate the General section.
- 5 From the Linear solver list, choose Direct.

Prepare a plot to be shown during the parametric sweep computation.

6 In the Study toolbar, click 🚛 Show Default Plots.

Parametric Sweep

- I In the Model Builder window, under Study I click Parametric Sweep.
- 2 In the Settings window for Parametric Sweep, locate the Output While Solving section.
- **3** Select the **Plot** check box.
- **4** In the **Study** toolbar, click **= Compute**.

RESULTS

Stress (solid)

Set up datasets to visualize the results for the full geometry. Note that two different types of datasets will be needed to show the magnetic fields and structural quantities.

Mirror 3D, symmetry yz-plane

- I In the **Results** toolbar, click **More Datasets** and choose **Mirror 3D**.
- 2 In the Settings window for Mirror 3D, type Mirror 3D, symmetry yz-plane in the Label text field.
- 3 Locate the Data section. From the Dataset list, choose Study 1/ Parametric Solutions 1 (sol2).

Mirror 3D, symmetry xz-plane

- I In the **Results** toolbar, click **More Datasets** and choose **Mirror 3D**.
- 2 In the Settings window for Mirror 3D, locate the Data section.
- **3** From the **Dataset** list, choose **Mirror 3D**, symmetry yz-plane.
- 4 In the Label text field, type Mirror 3D, symmetry xz-plane.
- 5 Locate the Plane Data section. From the Plane list, choose xz-planes.

Mirror 3D, antisymmetry xz-plane

- I Right-click Mirror 3D, symmetry xz-plane and choose Duplicate.
- 2 In the Settings window for Mirror 3D, click to expand the Advanced section.
- **3** From the **Vector transformation** list, choose **Antisymmetric**.

- 4 Select the **Define variables** check box.
- 5 In the Label text field, type Mirror 3D, antisymmetry xz-plane.

Study I/Parametric Solutions I (sol2)

- I In the Model Builder window, click Study I/Parametric Solutions I (sol2).
- 2 In the Settings window for Solution, locate the Solution section.
- **3** From the Frame list, choose Material (X, Y, Z).

Stress (solid)

- I In the Model Builder window, under Results click Stress (solid).
- 2 In the Settings window for 3D Plot Group, locate the Data section.
- **3** From the **Dataset** list, choose **Mirror 3D**, symmetry xz-plane.

Volume 1

- I In the Model Builder window, expand the Stress (solid) node, then click Volume I.
- 2 In the Settings window for Volume, locate the Expression section.
- 3 From the Unit list, choose MPa.

Deformation I

- I Right-click Volume I and choose Deformation.
- 2 In the Settings window for Deformation, locate the Scale section.
- 3 Select the Scale factor check box. In the associated text field, type 1.
- **4** In the **Stress (solid)** toolbar, click **O** Plot.

Magnetic Flux Density Norm (mfnc)

- I In the Model Builder window, under Results click Magnetic Flux Density Norm (mfnc).
- 2 In the Settings window for 3D Plot Group, locate the Data section.
- **3** From the **Dataset** list, choose **Mirror 3D**, **antisymmetry xz-plane**.

Multislice I

- I In the Model Builder window, expand the Magnetic Flux Density Norm (mfnc) node, then click Multislice I.
- 2 In the Settings window for Multislice, locate the Multiplane Data section.
- **3** Find the **x-planes** subsection. In the **Coordinates** text field, type 0.
- 4 Find the y-planes subsection. Clear the Coordinates text field.
- 5 Find the z-planes subsection. In the Coordinates text field, type -dm*1.1.

Streamline Multislice I

- I In the Model Builder window, click Streamline Multislice I.
- 2 In the Settings window for Streamline Multislice, locate the Multiplane Data section.
- 3 Find the x-planes subsection. In the Coordinates text field, type 0.
- 4 Find the y-planes subsection. Clear the Coordinates text field.
- 5 Find the z-planes subsection. In the Coordinates text field, type -dm*1.1.
- 6 Locate the Streamline Positioning section. In the Separating distance text field, type 0.015.
- 7 In the Magnetic Flux Density Norm (mfnc) toolbar, click 💿 Plot.

Plot the structural displacement magnitude in the plate.

Displacement (solid)

- I In the Model Builder window, right-click Stress (solid) and choose Duplicate.
- 2 In the Settings window for 3D Plot Group, type Displacement (solid) in the Label text field.

Volume 1

- I In the Model Builder window, expand the Displacement (solid) node, then click Volume I.
- 2 In the Settings window for Volume, locate the Expression section.
- 3 In the Expression text field, type solid.disp.
- 4 From the **Unit** list, choose **mm**.
- 5 Locate the Coloring and Style section. Click Change Color Table.
- 6 In the Color Table dialog box, select Rainbow>SpectrumLight in the tree.
- 7 Click OK.
- 8 In the Displacement (solid) toolbar, click 💿 Plot.

Evaluate the maximum structural displacement and the total force acting on the plate.

DEFINITIONS

Maximum I (maxopI)

- I In the Definitions toolbar, click 🖉 Nonlocal Couplings and choose Maximum.
- **2** Select Domain 3 only.

MAGNETIC FIELDS, NO CURRENTS (MFNC)

Force Calculation, for Postprocessing

- I In the Physics toolbar, click 🔚 Domains and choose Force Calculation.
- 2 In the Settings window for Force Calculation, type Force Calculation, for Postprocessing in the Label text field.
- **3** Select Domain 3 only.

STUDY I

In the **Study** toolbar, click *C* **Update Solution**.

RESULTS

Maximum displacement

- I In the Home toolbar, click 🚛 Add Plot Group and choose ID Plot Group.
- 2 In the Settings window for ID Plot Group, type Maximum displacement in the Label text field.
- 3 Locate the Data section. From the Dataset list, choose Study I/ Parametric Solutions I (sol2).
- 4 Click to expand the Title section. From the Title type list, choose Manual.
- 5 In the Title text area, type Maximum of relative vertical displacement (in %).
- 6 Locate the Legend section. Clear the Show legends check box.

Global I

- I Right-click Maximum displacement and choose Global.
- 2 In the Settings window for Global, locate the y-Axis Data section.
- **3** In the table, enter the following settings:

Expression	Unit	Description
maxop1(w/dm)	%	max(w/dm)

- 4 Click to expand the **Coloring and Style** section. Find the **Line markers** subsection. From the **Marker** list, choose **Cycle**.
- 5 In the Maximum displacement toolbar, click **O** Plot.

Total force

- I In the Home toolbar, click 🚛 Add Plot Group and choose ID Plot Group.
- 2 In the Settings window for ID Plot Group, type Total force in the Label text field.

3 Locate the Data section. From the Dataset list, choose Study 1/ Parametric Solutions 1 (sol2).

Global I

- I Right-click Total force and choose Global.
- 2 In the Settings window for Global, click Replace Expression in the upper-right corner of the y-Axis Data section. From the menu, choose Component I (compl)>Magnetic Fields, No Currents>Mechanical>Electromagnetic force (spatial frame) N>mfnc.Forcez_0 Electromagnetic force, z-component.
- 3 Locate the y-Axis Data section. In the table, enter the following settings:

Expression	Unit	Description
4*mfnc.Forcez_0	Ν	Total electromagnetic force, z-component

4 Locate the **Coloring and Style** section. Find the **Line markers** subsection. From the **Marker** list, choose **Cycle**.

Global 2

- I In the Model Builder window, right-click Total force and choose Global.
- 2 In the Settings window for Global, click Replace Expression in the upper-right corner of the y-Axis Data section. From the menu, choose Component I (compl)>Solid Mechanics> Reactions>Total reaction force (spatial frame) - N>solid.RFtotalz - Total reaction force, zcomponent.
- 3 Locate the y-Axis Data section. In the table, enter the following settings:

Expression	Unit	Description
-4*solid.RFtotalz	Ν	Total reaction force, z-component (with minus sign)

- **4** Locate the **Coloring and Style** section. Find the **Line style** subsection. From the **Line** list, choose **Dashed**.
- 5 From the Color list, choose Red.
- 6 In the Total force toolbar, click 💿 Plot.